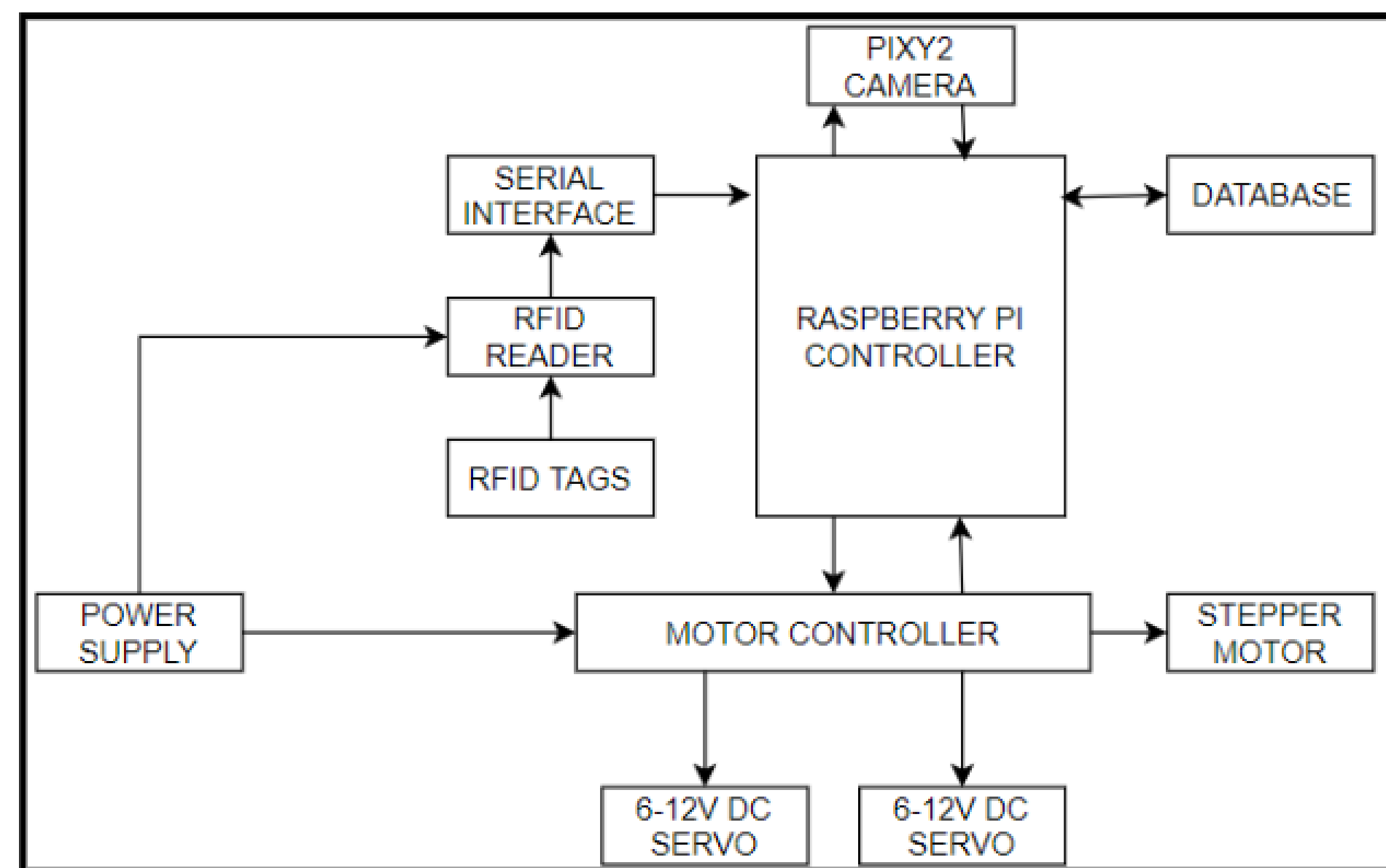


Objective

The objective of AITURRS is to create a self-operating robot capable of maneuvering around an environment using the Pixy 2 vision sensor. Using a mounted RFID scanner, the robot reads RF tags associated with individual assets, and determines the location and ID of the asset with a microcontroller. It transmits that data wirelessly to an online database holding the location information of all items in inventory.



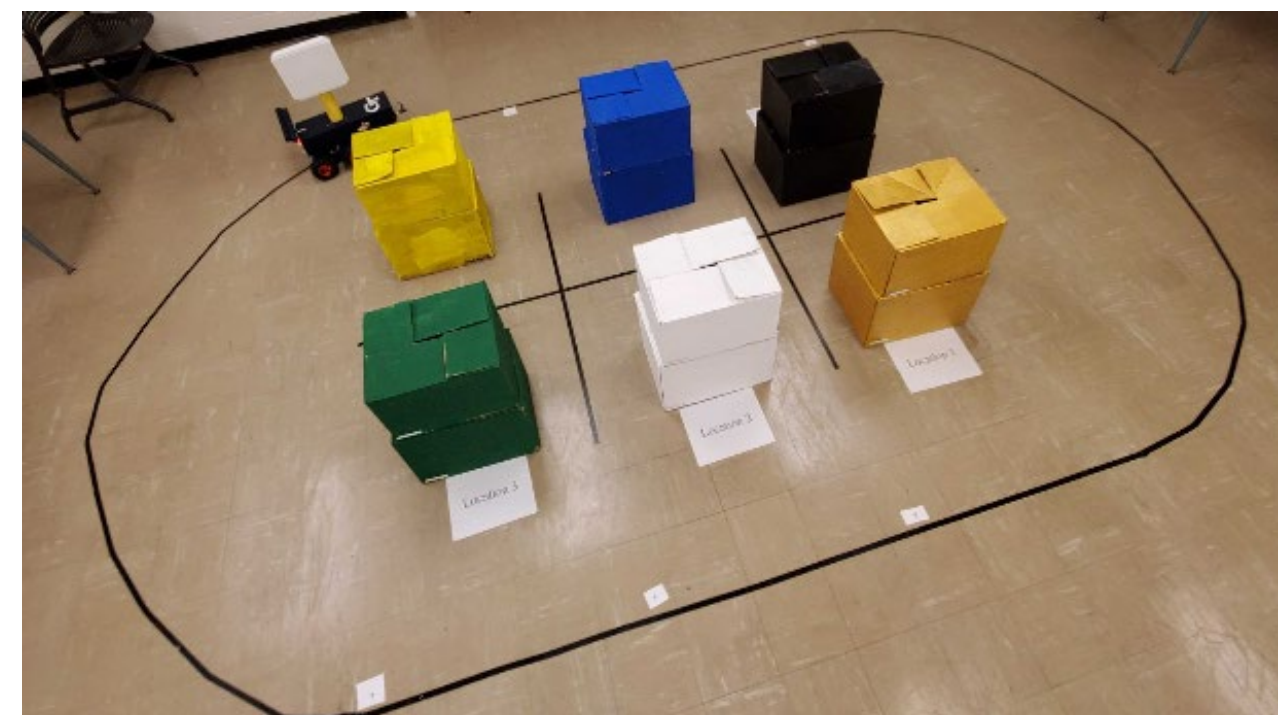
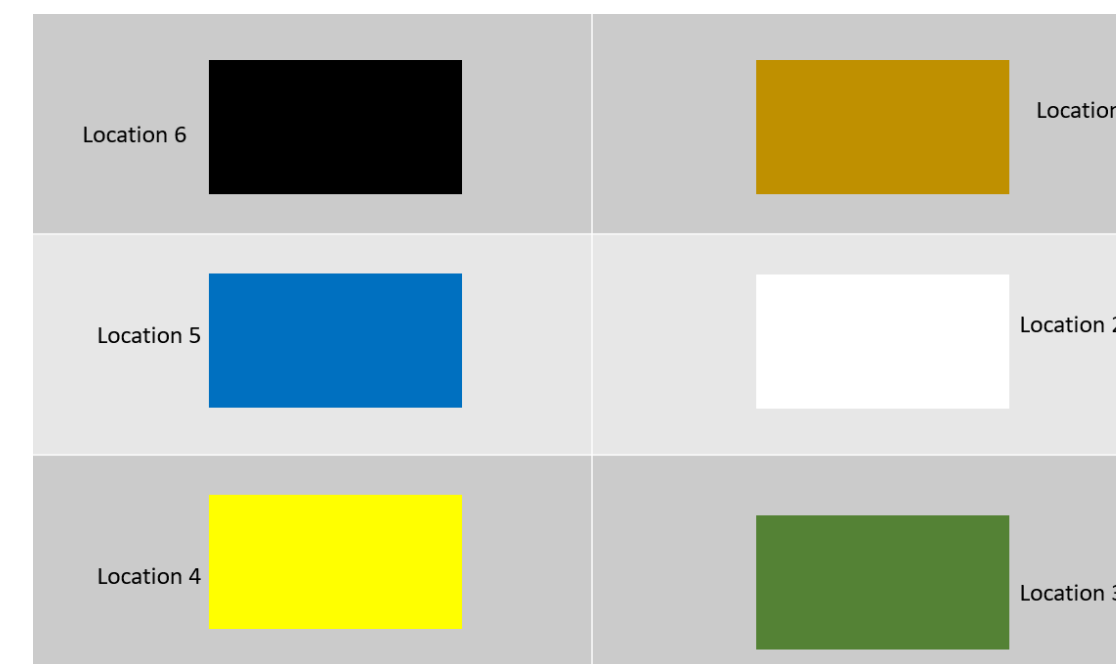
Prototype Materials and Cost

Part	Cost
Raspberry Pi 4	\$118.90
Pixy Camera	\$60.00
Motor Driver	\$25.00
915 MHz Circular Polarity RFID Panel Antenna	\$500.00
Chassis	\$180.00
NiCD RC Batteries	\$40.00
Total	\$923.90

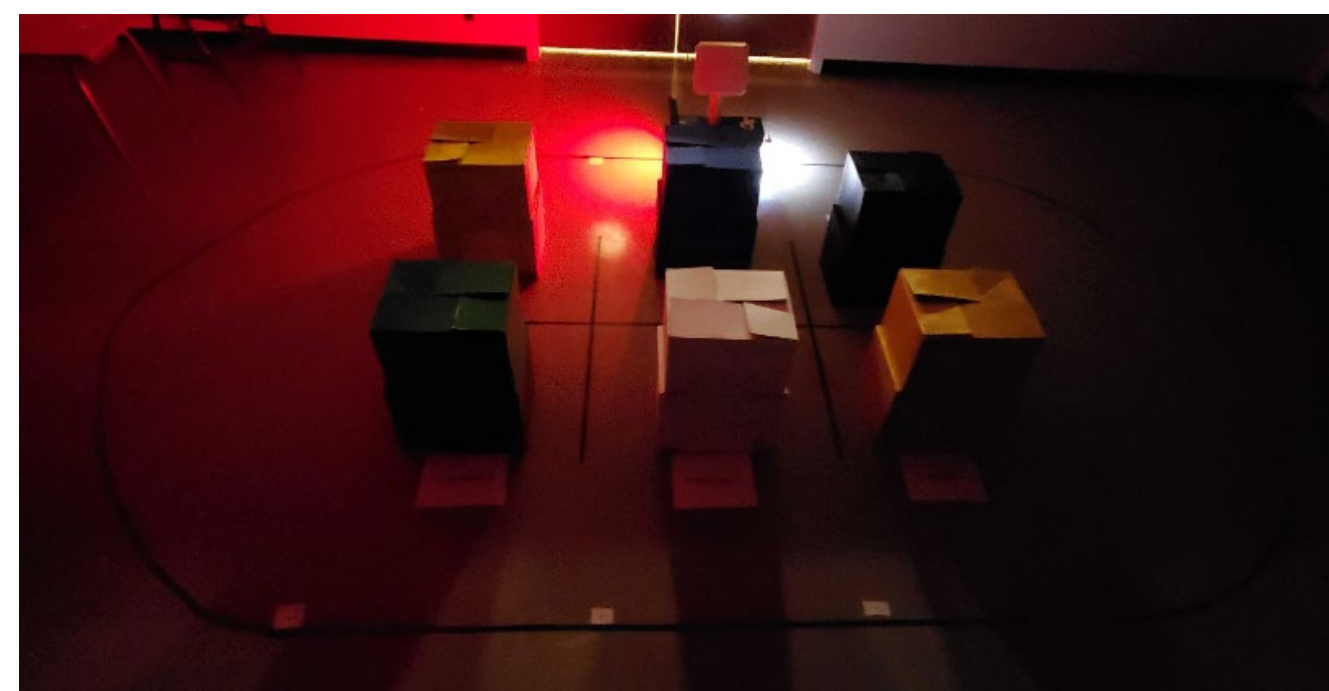
Specifications

Feature	Specification
Bandwidth	865-928 MHz
Transmit Power	+10 - +31.5 dBm
Max Receive Sensitivity	-84 dBm
Power Supply	24Vdc/2.1A

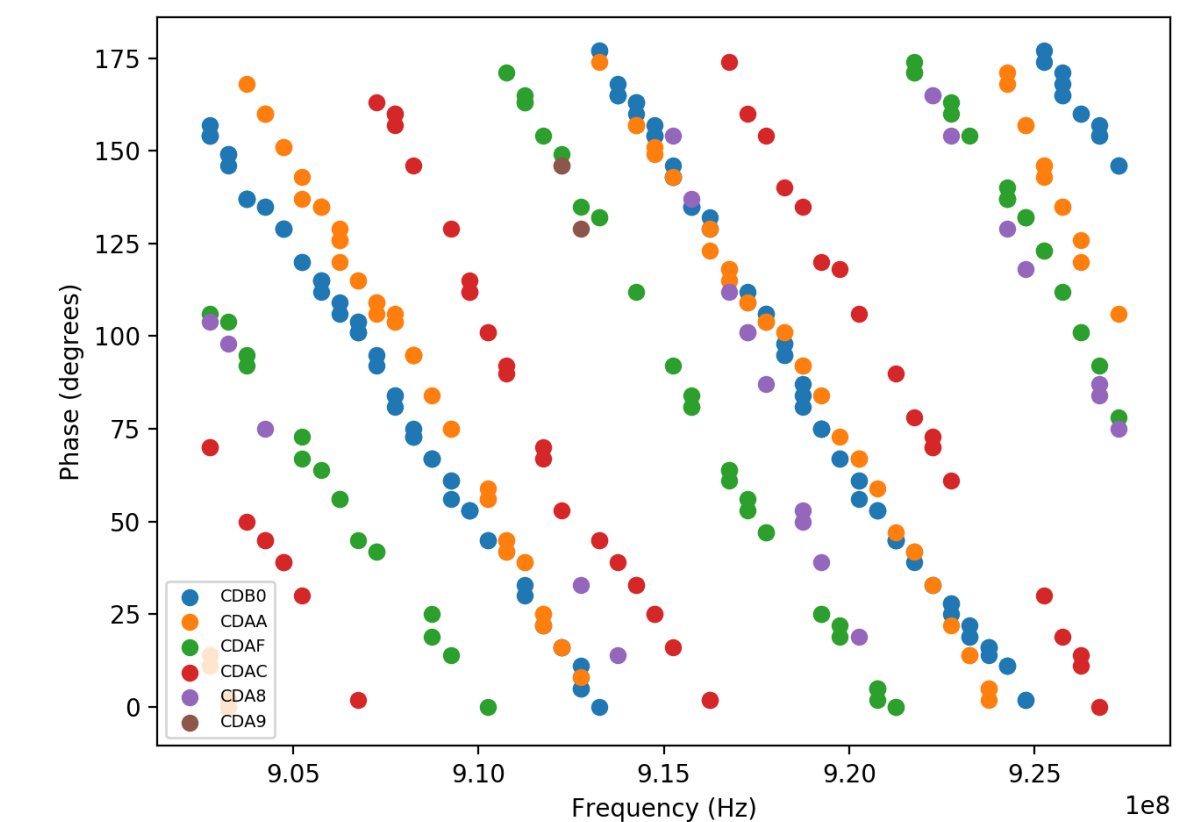
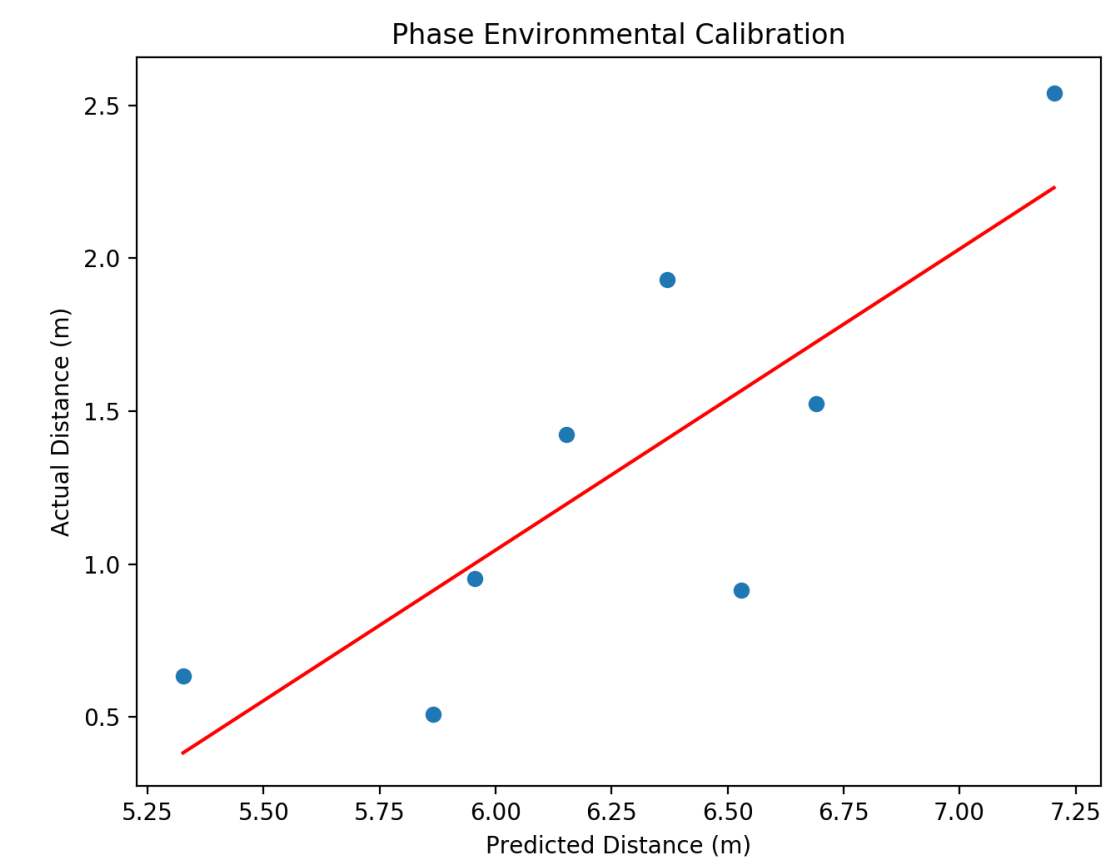
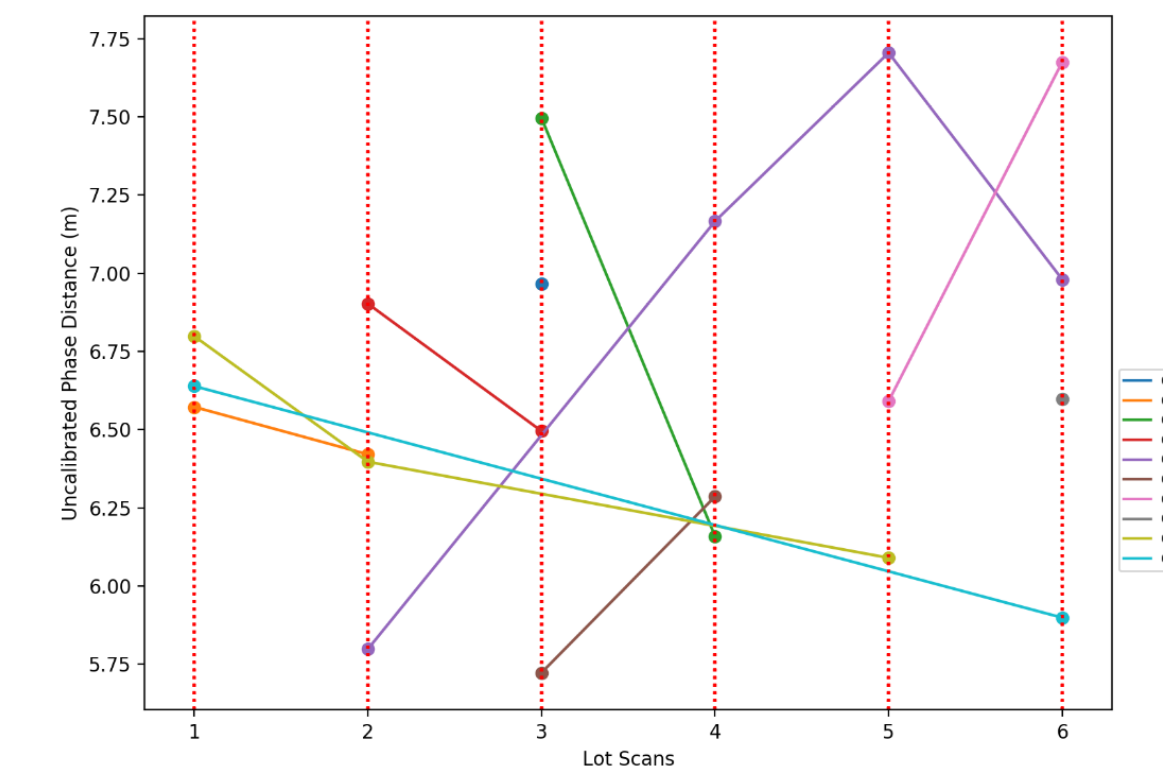
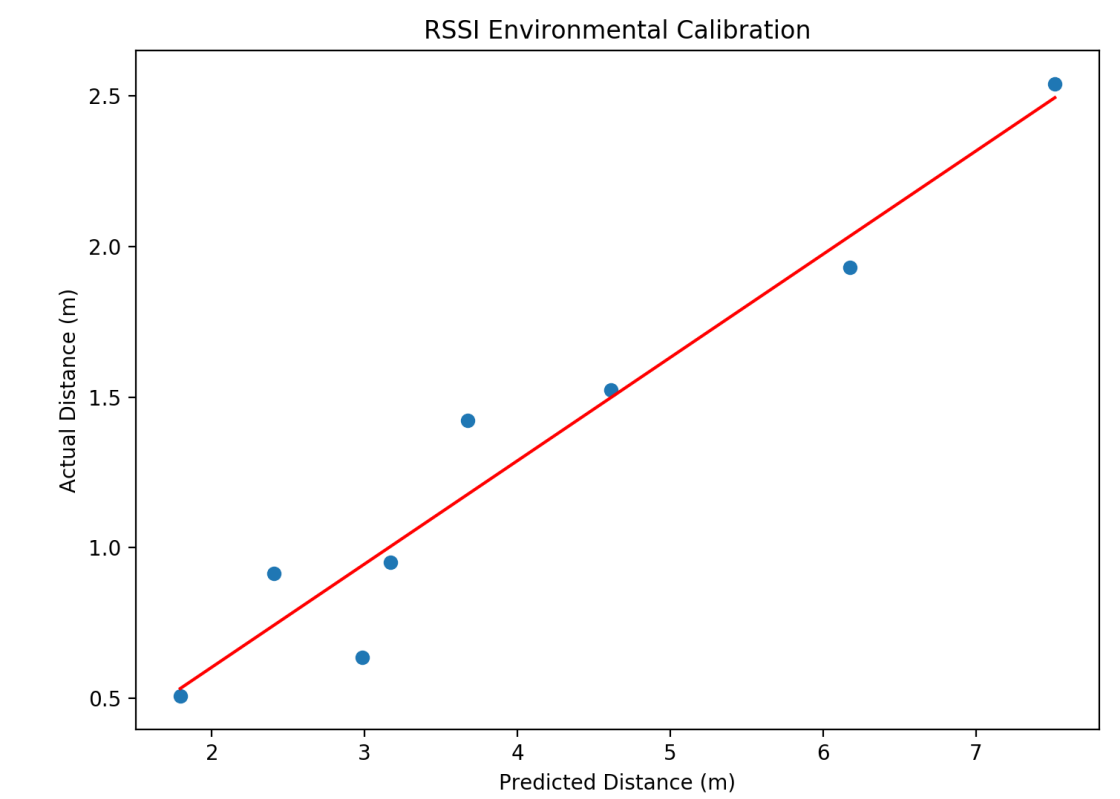
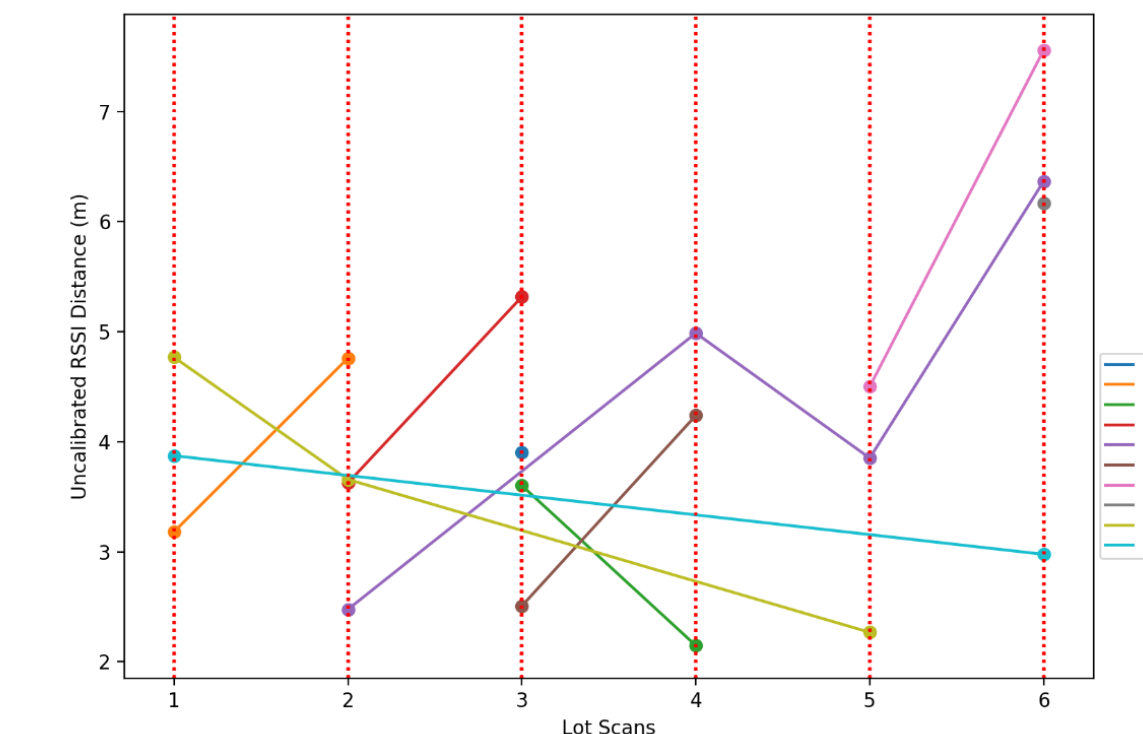
Testing Set-Up



Night Tracking Capabilities



Results



Contact

Visit our website to learn more about our project:
<https://qr.go.page.link/y3Asx>

